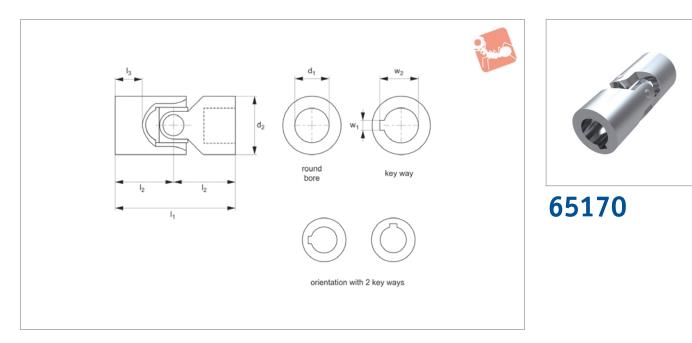


Single Universal Joint

Steel

Universal Joints



Material

Steel (9SMnPb28k, no. 10718). Bearing type: plain bearing.

Technical Notes

To DIN 808/7551. Maximum bending angle 45° per joint, Max. drive speed of 1000 rpm.

Tips

Single universal joints are used where shafts are off-set towards each other. Product variations available on request, for square bores change the suffix to SQ for square bores or HX for hex bores. For stainless steel see 65186

For needle roller bearings see part number

Order No. Bore dia. d1 tol. H7 d2 I1 I2 65170.W0010 Round bore 10 16 52 26 65170.W0012 Round Bore 12 22 62 31 65170.W0016 Round Bore 16 25 74 37				
65170.W0012Round Bore1222623165170.W0016Round Bore16257437	l ₃ to	w ₁ bl. JS9	w ₂	Weight g
65170.W0016 Round Bore 16 25 74 37	15	-	-	50
	18	-	-	120
	21	-	-	200
65170.W0020 Round Bore 20 32 86 43	24	-	-	350
65170.W0025 Round Bore 25 42 108 54	31	-	-	800
65170.W0030 Round Bore 30 50 132 66	38	-	-	1200
65170.W0040 Round Bore 40 70 166 83	47	-	-	2900
65170.W0210 With keyway 10 16 52 26	15	3	11.4	50
65170.W0212 With keyway 12 22 62 31	18	4	13.8	120
65170.W0216 With keyway 16 25 74 37	21	5	18.3	200
65170.W0220 With keyway 20 32 86 43	24	6	22.8	350
65170.W0225 With keyway 25 42 108 54	31	8	28.3	800
65170.W0230 With keyway 30 50 132 66	38	0	22.2	1200
65170.W0240 With keyway 40 70 166 83		8	33.3	1200



Materials Handling

Universal Joints

overview



Parts overview

UNIVERSAL JOINTS

Single Universal Joints

Available with plain bearings or needle roller bearings. Plain bore and keyed bores stocked as standard, hex or square shaped bores on request. Bore diameters 6mm up to 50mm.





Quick Release Universal Joints

Quick change mechanism one end of the joint to allow rapid connection and release of the shaft, ideal when time is critical. Bore diameters 8mm up to 30mm.

Double Universal Joints

Available with plain bearings or needle roller bearings. Plain bore and keyed bores stocked as standard, hex or square shaped bores on request. Bore diameters 6mm up to 50mm.

Stainless Steel Universal Joints

Single and double universal joints with plain bearings and plain bores. Keyed, hex or square shaped bores available on request. Bore diameters 6mm up to 30mm.



Universal Joint Bellows

Available for both single and double universal joints, bellows are used to cover and protect the joints. Available to protect joints up to 58mm outside diameter.

Telescopic Universal Joints

Two universal joints connected by a sliding splined shaft with the ability to extend, allowing adjustments in length during installation. Bore diameters 10mm up to 30mm.



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Universal Joints

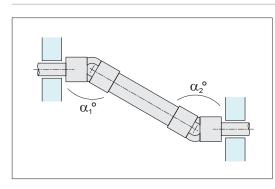
Materials Handling

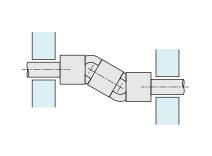
When one single joint is coupled with two shafts (of which the driving one is rotating at a constant speed) forming an angle, a periodic variation of the driven shaft is caused with exactly four fluctuations per revolution.

The difference between the maximum and the minimum speed of the driven shaft depends on the angle formed by the two shafts. The difference grows with the an increase of the angle a°. To have a homokinetic transmission, either two opposite single joints (ensuing that that the two central yokes lie on the same plane and the angles are equal) or a double joint need to be fitted. The irregularity caused by the former articulation is cancelled by the latter. The overall length resulting from the coupling of the two single joints can be reduced by using a double joint. In other words, the double joint is to be considered as the shortest homokinetic transmission.

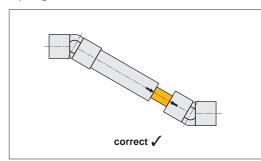
For low speed applications (Max. 1000 rpm), joints with plain bearings (rubbing bearings) are suggested. They are able to support shock loads, motion reversals, irregular runnings and relatively high torgues. The working angles must be be restricted when using at speeds between 500 - 1000 rpm. Please consult our technical department if you have such an application.

For high rotation speeds, relatively low torgues or wide angles, joints with needle roller bearings are preferred. They can reach 4000 RPM dependent on the angle.

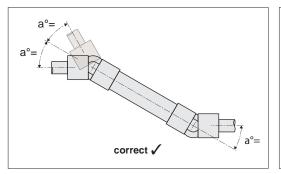




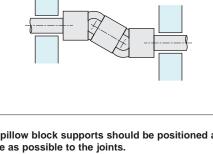
To obtain a uniform rotary motion always use either two opposite single joints or one double joints. $\alpha_1 = \alpha_2$.



When using two opposite single joints ensure the alignment of the inside yokes.



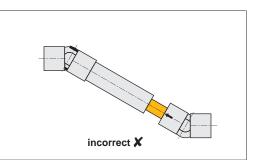
It is essential that the two bending angles a° are equal.



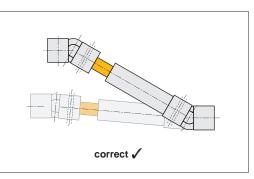


Dynamic basic load

The pillow block supports should be positioned as close as possible to the joints.



In extensible transmissions make sure that the arrows are perfectly aligned.



3







How to read diagrams

The joint capacity to transmit a regular torque at a constant load with no shocks, for a long period, mainly depends on the number of revolutions per minute and the inclination angle a° of the two axes. The diagrams on the following pages are based on this. Each curve corresponds to the joint size (outside diameter "D") and represents the torque that the joint can transmit depending on speed and working angle a°.

The diagrams can be directly read if angle (a°) is 10°. For wider angles, torques are reduced, therefore these are to be corrected using the correction vales (F) relating to the angle shown in the table.

Important Note: Diagrams' values are merely indicative and refer to the single joints only. When choosing a double joint, you have to consider that they can transmit a torque about 10% lower than the same sized single joints. Each application has its own particular motion characteristics, such as: shock loads, motion reversals, connected masses, kind of starting, presence of elastic joints, stops and starts, etc., that have to be considered when choosing the joint.

Working angle a°	Correction value F		
5°	1,25		
10°	1,00		
15°	0,80		
20°	0,65		
25°	0,55		
30°	0,45		
35°	0,38		
40°	0,30		
45°	0,25		

Example

Known: Power = 0,65 kWRPM = 230

With working angle a 10°, F = 1, we get point P. Torque = 27 Nm corresponding to joint size "D" = 25/26mm = Types 65170.W0016 and 65172.W0012

With working angle a 30°, F = 0,45 (kW 0,65: 0,45 = 1,44 kW) we get point Torque = 60 Nm corresponding to joint size "D" = 32mm = Types 65170.W0020 and 65172.W0016

Consider that:

Torque in Nm = 9550 x Power (kW) RPM
Torque in Nm = 7020 x Power (HP)
RPM

1 kW = 1,35 HP 1 HP = 0,736 kW 1 Kgm = 9,81 Nm 1 Nm = 0,102 Kgm

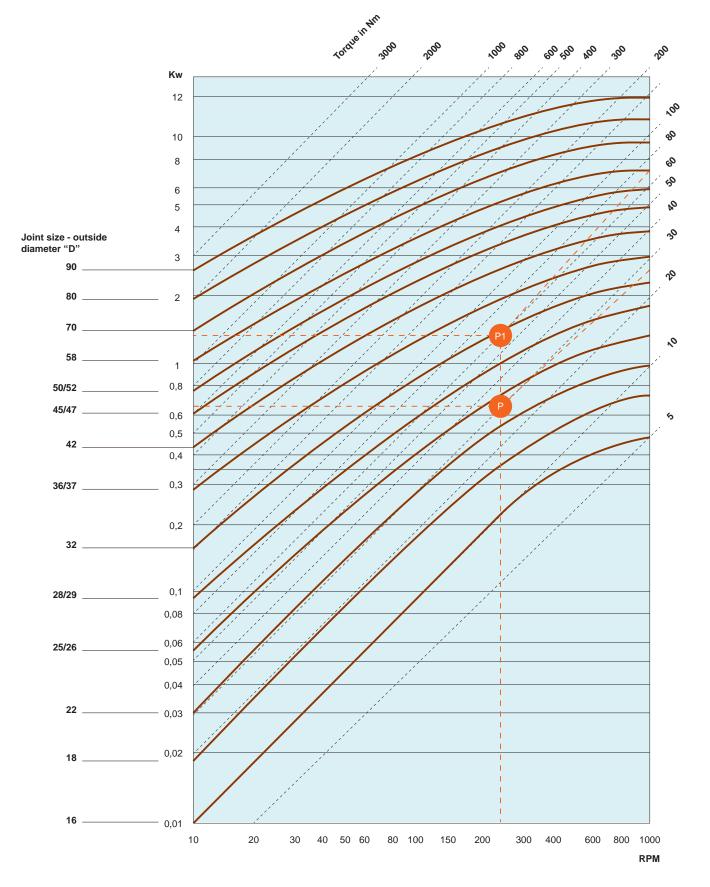


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Torque Ratings for Plain Bearing Universal Joints

Materials Handling





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